Macro II

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Introduction

- ► Today: reintroduce stochastic neoclassical growth model.
- Jumping off point for most modern macro models.
- Introduce solution techniques.
- Homework (really will be) on my website.

Model environment

- Every macro presentation should have an environment slide.
- This details the following:
 - 1. preferences
 - 2. technology
 - 3. markets
- Then jump into individual problem.
- We will go through each of these.

Consumer's Problem

 consumers in this economy maximize the expected value given by

$$\mathbb{E}\left[\sum_{t=0}^{\infty}\beta^{t}u(c_{t})\right]$$

- u is a bounded, continuous and strictly increasing utility function.
- $\beta \in (0, 1)$ is a discount factor.

subject to

$$y_t \ge c_t + \left[\underbrace{k_{t+1} - (1 - \delta)k_t}_{=i_t}\right]$$

Resource Constraints

$$y_t \ge c_t + i_t$$
 $k_{t+1} = (1 - \delta)k_t + i_t$

- An agent owns an amount $y_t \in \mathbb{R}_+ := [0, \infty)$ of consumption good at time t.
- Output can either be consumed or invested.
- When the good is invested, it is transformed one-for-one into capital.

Technology

$$y_{t+1} = f(\gamma_{t+1}, k_{t+1}), \ \gamma_{t+1} \sim \Phi$$

- *f* : ℝ²₊ → ℝ₊ is the production function which is increasing and continuous in *k* and *γ*.
- Production is stochastic, in that it depends on a shock \(\gamma_{t+1}\) realized at the end of the current period t.
- Calibration

$$\begin{aligned} \gamma_{t+1} &= e^{\sigma \epsilon_{t+1}}, \epsilon_{t+1} \stackrel{i.i.d.}{\sim} \mathcal{N}(0,1), \ \sigma > 0\\ f(k_{t+1}, \gamma_{t+1}) &= \gamma_{t+1} k_{t+1}^{\alpha}\\ \delta &= 1 \end{aligned}$$

Optimization

$$\max_{\{c_t, k_{t+1}\}_{t=0}^{\infty}} \mathbb{E}\left[\sum_{t=0}^{\infty} \beta^t u(c_t)\right]$$

s.t. $y_t \ge c_t + k_{t+1} \forall t$ (Resource Constraint)
 $y_{t+1} = f(k_{t+1}, \gamma_{t+1}), \ \gamma_{t+1} \stackrel{i.i.d.}{\sim} \Phi \forall t$ (Technology)
 $c_t \ge 0 \ k_{t+1} \ge 0 \forall t$ (Non-negativity Constraint)
 $y_0 = \bar{y}_0 \ given$

Sequential Problem (SP)

$$\max_{\substack{\{c_t\}_{t=0}^{\infty}}} \mathbb{E}\left[\sum_{t=0}^{\infty} \beta^t u(c_t)\right]$$

s.t. $y_{t+1} = f(k_{t+1}, \gamma_{t+1}), \ \gamma_{t+1} \stackrel{i.i.d.}{\sim} \Phi \ \forall t$
 $y_t \ge c_t + k_{t+1} \forall \ t$
 $y_0 = \overline{y}_0 \text{ given}$

- Resource constraint holds with equality b/c u' > 0.
- ▶ *y*_t summarizes state of world at the start of each period.
- c_t is chosen by the agent each period after observing the state.

Functional Equation (FE)

(SP) is an infinite-dimensional optimization problem. Instead, find a time-invariant solution to functional equation:

$$v^{*}(y) = \max_{c \in [0,y]} \left\{ u(c) + \beta \int v^{*} (f(k',\gamma)) \phi(d\gamma) \right\}$$
$$y = c + k'$$
$$y' = f(k',\gamma)$$

Solution v^* , evaluated at $y = \bar{y}_0$, gives the value of the maximum in (SP).

Steady State

- ► Hard to characterize dynamics/solve model (find c(t), k(t)∀ t)
- Instead, characterize steady-state.

•
$$c = c' = c^*$$
, $k = k' = k^*$

▶ pick u(c) = ln(c), $f(k, \gamma) = e^{\sigma \epsilon} k^{\alpha}$ and $\epsilon \sim N(0, 1), \sigma = 1$. ▶ then

$$\frac{1}{c} = \beta \mathbb{E}[(\alpha e^{\epsilon'} k'^{\alpha-1}) \frac{1}{c'}]$$

In steady state:

$$\frac{1}{c^*} = \beta(\alpha \bar{\gamma} k^{*\alpha-1}) \frac{1}{c^*}$$

We will solve for the stochastic steady state.

i.e., the steady-state if the aggregate shock were at its mean.

Steady State

This leaves us with capital:

$$1 = \beta (\alpha \bar{\gamma} k^{*\alpha-1})$$
$$k^* = (\frac{1}{\bar{\gamma} \alpha \beta})^{\frac{1}{\alpha-1}}$$
$$k^* = (\bar{\gamma} \alpha \beta)^{\frac{1}{1-\alpha}}$$

Now consumption from the budget constraint:

$$\begin{split} c^* + k^* &= \bar{\gamma} k^{*\alpha} \\ c^* &= \bar{\gamma} k^{*\alpha} - k^* \\ c^* &= \bar{\gamma} (\bar{\gamma} \alpha \beta)^{\frac{\alpha}{1-\alpha}} - (\bar{\gamma} \alpha \beta)^{\frac{1}{1-\alpha}} \end{split}$$

Dynamics



$$c' = \beta(\alpha \bar{\gamma} k^{' \alpha - 1})c$$

 $k' = \bar{\gamma} k^{lpha} - c$

We have two dynamic variables: c and k.

The behavior of this system will depend on their dynamics.

At steady-state:

$$1 = \frac{c'}{c} = \beta(\alpha \bar{\gamma} k^{\alpha - 1})$$
$$1 = \frac{k'}{k} = \bar{\gamma} k^{\alpha - 1} - \frac{c}{k}$$

If both hold, we are in steady-state, if not, dynamics can vary.

Dynamics



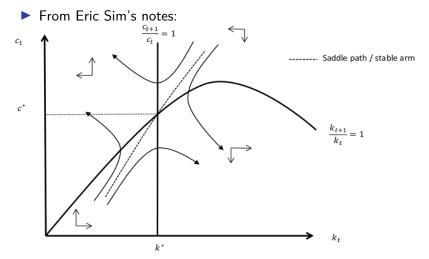
$$egin{aligned} c' &= eta(lphaar\gamma k^{lpha-1})c\ k' &= ar\gamma k^lpha - c \end{aligned}$$

- Small *c*: second equation dictates that capital increases.
- Small k: first equation dictates that consumption increases.
- Reverse is true.

Phase Diagram

► Dynamics:

$$egin{aligned} c' &= eta(lphaar{\gamma}k^{'lpha-1})c\ k' &= ar{\gamma}k^lpha - c \end{aligned}$$



Solving for dynamics

Recall contraction mapping

• If T is a contraction mapping with modulus β , then

1. there exists a unique fixed point v^* , and

$$v^* = Tv^*$$

$$v^*(y) = \max_{c \in [0,y]} \left\{ u(c) + \beta \int v^* (f(k',\gamma)) \phi(d\gamma) \right\}$$

$$y = c + k'$$

$$y' = f(k',\gamma)$$

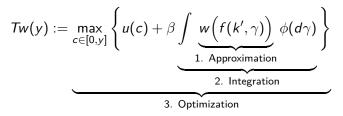
2. for any v_0 and any $n \in \mathbb{N}$,

$$\rho(T^n v_0, v^*) \leq \beta^n \rho(v_0, v^*)$$

- Yields an is a policy function $\sigma^*(y) = \operatorname{argmax}\{v(y)\}$
- We can apply this in two ways: analytically or computationally.

Computation

How can we implement Bellman operator on our computer?



where w is a function that approximates v.

Approximation

- Approximate an analytically intractable real-valued function f with a computationally tractable function f
- given limited information about f.
- Divide the approximation domain of the function into finite number of sub-intervals and approximate the original function in each of the intervals.
 - The points on the domain which separate the intervals are called grid points.
 - We use the value of the function at each grid point to approximate the original function.
- Another way to think about it: sampling from domain of the function at n nodes. As n → ∞, f → f

Approximation II

In order to figure out Bellman operator, we need to approximate an analytically intractable real-valued function w.

$$Tw(y) := \max_{c \in [0,y]} \left\{ u(c) + \beta \int w \left(f(k',\gamma) \right) \phi(d\gamma) \right\}$$

Interpolation

- 1. Determine an approximation domain of w.
- 2. Pick *n* (often evenly spaced) nodes, produces n 1 intervals.
- 3. Approximate the original function *w* in each of the resulting intervals using a polynomial.
- Grid search
 - 1. Determine an approximation domain of w.
 - 2. Pick *n* nodes, produces n 1 intervals.
 - 3. Evaluate function at each node and pick maximum.

Integration

In order to figure out Bellman operator, we need to evaluate continuation value.

$$Tw(y) := \max_{c \in [0,y]} \left\{ u(c) + \beta \int w(f(k',\gamma)) \phi(d\gamma) \right\}$$

► One approach: Monte Carlo integration: Given a random sample of size n, {γ_i}ⁿ_{i=1}

$$\frac{1}{n}\sum_{i=1}^{n}\frac{w(f(k',\gamma_i))\phi(\gamma_i)}{\phi(\gamma_i)} \xrightarrow{p} \int w(f(k',\gamma))\phi(\gamma)d\gamma$$

 Better approach: Gaussian Quadrature (for normally distributed shocks and from related families)

Optimization

- Find the minimum of some real-valued function of several real variables on a domain that has been specified.
 - Derivative methods: Newton's method, etc.
 - Derivative free: Golden section search, Grid search: pick maximizing node.
- Finding the global minimum can be challenging.
 - The function can have many local minima.
 - Curse of dimensionality & curvature of problem (when problems approach boundaries).

Conclusion

- Alternative: guess and verify (method of undetermined coefficients).
- We will cover this next time.
- Midterm next Wednesday!
- Check website for homework (totally, I promise).